SOFTLINK

WIRELESS COMMUNICATION SYSTEM
WACO WM868

WM868-SJ-MS

Revision 1.0

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1 Introduction

This document describes features, parameters and setting possibilities of the WM868-SJ-MS module, which is used for data collection from battery powered modules (such as WM868-SI/SA, WM868-TI/TE, WM868-MDA/MDB/SEA and possibly others), conversion od gathered data into the M-Bus format, and handing over the data to superior M-Bus control unit („master") in M-Bus format.

1.1 WACO communication system

WACO (Wireless Automatic Collector) is radio frequency (RF) communication system intended especially for the remote reading of consumption meters (smart metering area), automatic data collection from sensors (telemetry area), and bi-directional data transfer among control, sensing and actuating elements in automatic control systems (industrial automation area). Installed WACO radio-frequency elements create local radio network covering object of interest (flat, house, building, compound...) or required area (street, city...).

WACO RF network has a **„mesh"** type of topology, where in reach of each radio element there could be placed several other network elements that could operate also as repeaters of received signal. In this kind of network there are typically several possible communication paths between the central point and other single elements of the network. WACO network communication protocol was designed to provide a **maximum data transmission reliability and redundancy** with using of multiple communication paths, but at the same time the network is protected against circularity and multiplication of messages by sophisticated algorithms so that the network keeps also a **high performance** even with high number of radio elements working in one network.

WACO communication protocol was designed in compliance with a telecommunication standard **ISO/OSI model** that ensures a high variability of supported applications.

WACO radio-frequency devices (hereinafter „radio modules") are equipped with **various types of input/output interfaces** that enables integration of various connected device (meters, sensors, actors...) into one network.

WACO communication system includes also special communication devices - **WACO GateWays**, that enable receiving of radio messages from the local WACO RF-network and transfer them to the local or remote computer through the serial line or Internet and (in inverse direction) receiving messages from the serial line/Internet and broadcast them into „its" RF-network.

1.2 Module usage

The WM868-SJ-MS is intended for collection of readings from meters and sensors within WACO remote reading system and conversion of collected data into the M-Bus communication protocol, commonly used in metering and smart metering area. Category of WACO WM868 devices with such functionality is generally called **„WACO collecting unit"**.

Principle of data conversion in WM868-SJ-MS module is described in the figure 1.

As evident from the picture, the WM868-SJ-MS module receives data from spontaneously broadcasting modules of WACO network, that are in „broadcast" mode and their messages are coded in WACO/NEP protocol. There is a „Table of virtual M-Bus devices" stored in the WM868-SJ-MS module memory, that contains records of all meters and their variables that should be read, together with the identification of these meters/variables in M-Bus remote reading system. The module continuously stores received data (i.e. current statuses of variables) into this table. On the M-Bus Master's request for status of any meter/variable recorded in the table, the module sends an answer with the last received status in M-Bus format though the M-Bus Slave interface.

Using of WACO collecting unit enables incorporation of even simple meters/sensors, that are not equipped by sophisticated M-Bus interface, into the remote reading system according to the advanced M-Bus standard. Collection of data from such meters/sensors is procured by WACO collection unit, that acts as their „agent" within M-Bus system.

The WACO collecting unit of WM868-SJ-MS type enables collecting up to 50 variables from up to 50 devices. The data can be received from all types of WACO-modules, that use "SISA_TX" (port 37) application for broadcasting of data. That are primarily battery powered modules of WM868-SI/SA, WM868-TI/TE/TES, WM868-MDA/MDB, or WM868-SEA series in various variants and modifications, as well as some other types of modules unlisted here. The transferred variable is typically a current status of meter's consumption register (or sensor's status) , but it could be also meter/sensor identification (serial number). Detailed information about the message content can be found in paragraph 3.7.
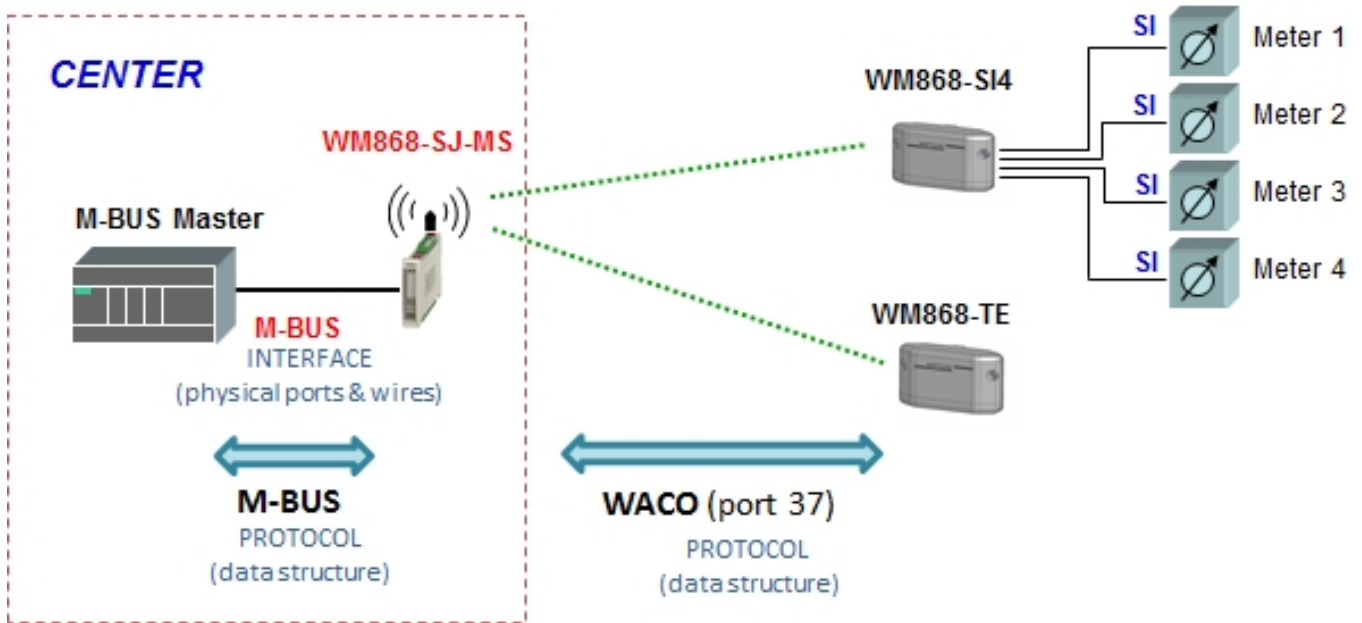
Figure 1: Principle of data conversion in WACO collecting unit WM868-SJ-MS

1.3 Hardware features and power supplying

The module is enclosed in a plastic casing adapted for mounting on a DIN-rail. The box has a standard „circuit breaker" profile and width of two standard DIN-modules. The module is equipped with a two-wire screw-on terminal ("M-BUS") for connecting of M-Bus data bus.

The module needs an external power supply 24V DC. For connecting of the power supply there is a screw-on terminal with marked voltage polarity. Power supplying must follow all the safety requirements according to the appropriate standards. Maximum current consumption of the module (for voltage of 24 V) is up to 50 mA, the module is protected on the power supply input by reversible fuse with release current of 300 mA.

The module cannot be used in exteriors without additional covering. External appearance of the WM868-SJ-MS module is shown in the figure 2.
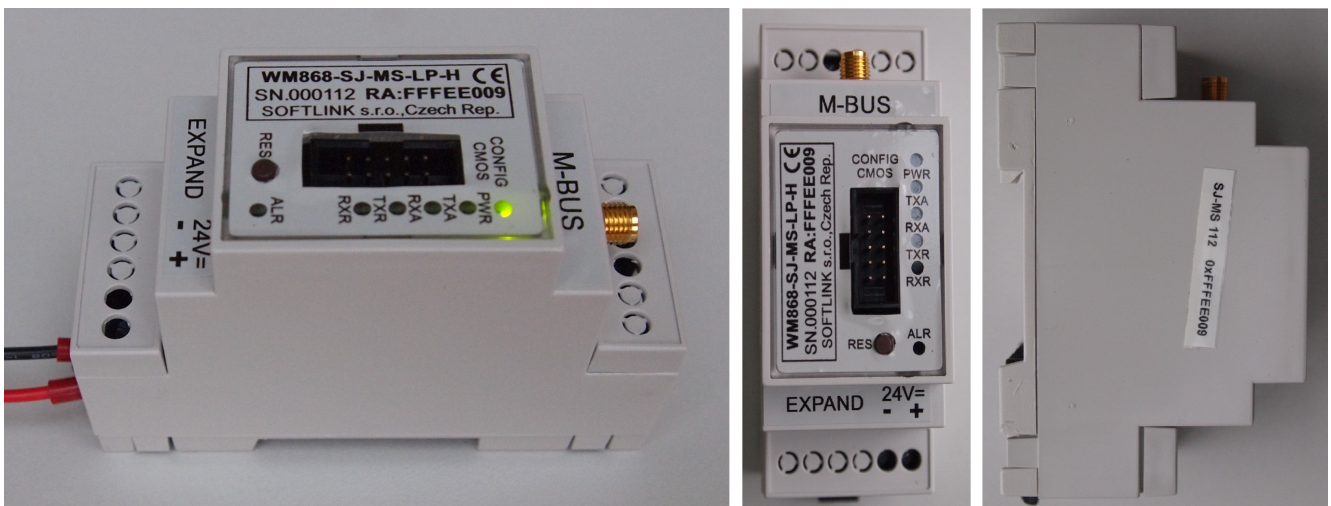
Figure 2: View of the WM868-SJ-MS module

2 Technical parameters overview

Overview of WM868-SJ-MS module technical parameters is shown in the Table1 below.

Table 1: Overview of WM868-SJ-MS module technical parameters

RF subsystem parameters		
Frequency band	868,0 - 868,6	MHz
Modulation	FSK	
Number of channels	3	
Bandwidth	200	kHz
Transmitting power	25	mW
Receiver sensitivity	106	dBm
Communication protocol	WACO	
Transmission speed	38400	Baud
Antenna connector	SMA female	
Antenna characteristic impedance	50	Ω
Configuration interface RS232		
Transmission speed	19200	Baud
Operation mode	asynchronous	
Transmission parameters	8 data bits, 1 stop bit, none parity	
Signal level	TTL/CMOS	
Data interface		
Interface type	M-Bus Slave	(two clamps))
Transmission speed	300 ÷ 9600	Baud
Operation mode	asynchronous	
Transmission parameters (default)	8 data bits, 1 stop bit, none parity	
Signal level	dle EN1434-3, EN60870	
Nominal current consumption	1,5	mA
Power supplying		
External power supply	24	V ±10%
Input power	4	W
Weight and dimensions		
Width	35	mm
Height	90	mm
Depth	58	mm
Weight	cca 150	g
DIN casing size	2 modules	
Storage and installation conditions		
Installation environment (by ČSN 33 2000-3)	normal AA6, AB4, A4	
Operation temperature range	(-20 ÷ 50)	°C
Storage temperature range	(0 ÷ 70)	°C
Relative humidity	90	% (w/o condensation)
Degree of protection	IP20	
Signaling and control		
Power signaling	"PWR"	green LED
Signaling of RF transmission	"TXA"	yellow LED
Signaling of RF reception	"RXA"	yellow LED
Signaling of bus transmission l	"TXR"	yellow LED
Signaling of bus reception	"RXR"	yellow LED
Signaling of RF signal collision	"ALR"	red LED
System restart button	"RES"	

3 Configuration of the WM868-SJ-MS module

Configuration parameters of the WM868-SJ-MS module can be displayed and changed from the common computer (PC) by one of these methods:

- with using of **"USB-CMOS"** converter and configuration cable connected to the module
- wirelessly, with using of WM868-RFU radio-frequency communication gateway

Technique of interconnection of the module with configuration computer and general rules of configuration are described in detail in the section 3.1 "Configuration of the module with using of the configuration cable". The description and meaning of all configuration parameters that can be checked and changed by cable can be found in the section 3.5 "Setting of WM868-SJ-MS parameters via configuration cable". Description of interconnection of the WM868-RFU RF-communication gateway with computer and general rules of configuration **via radio** are described in the section 3.2 "Configuration of the module via radio". The description and meaning of the parameters that can be changed via radio can be found in the section 3.6 "Setting of WM868-SJ-MS parameters via radio".

3.1 Configuration of the module with using of the configuration cable

Configuration of the module can be performed by using of any PC with MS Windows or Linux operating systems interconnected by configuration data cable. The module's communication interface is of RS-232 (COM) type with CMOS signal level. The "CONFIG CMOS" configuration connector is placed on the module's front panel.

3.1.1 Connecting of module to computer

Configuration can be performed by using of common USB port of the computer. For the interconnection with a USB port of computer it is necessary to use an manufacturer's original configuration cable with "USB-CMOS" converter (see Figure 4). This converter creates a virtual serial port through the USB interface and adapts voltage levels of the module's configuration port to the standard USB port of common PC. So as to be able to create a virtual serial connection via USB interface, there must be a relevant driver installed in the computer operation system. After the "USB-CMOS" converter is connected to computer for the first time, operating system will find and install appropriate generic driver of "USB Serial Device" category automatically. After driver installation is completed, the device will appear in the "Ports (COM and LPT)" section of the "Device Manger" window as "USB Serial Device (COMx)" (see figure 3).
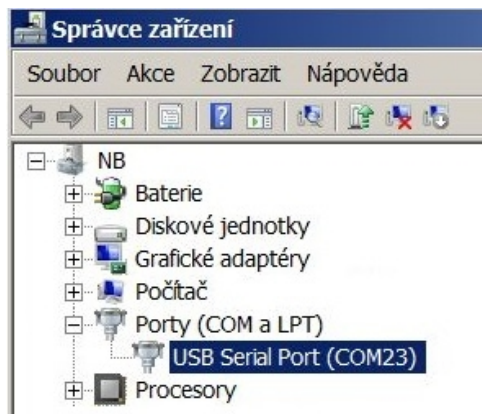
Figure 3: Appearance of the USB-CMOS converter in Windows "Device Manager"

As some of the older MS Windows versions do not support a generic driver for USB serial ports, the automatic installation of the driver could fail (system reports "Driver software installation failure", or "driver not found"). In this case there is necessary to install the driver manually, following the steps in paragraph 3.3 "Installation of USB-CMOS converter driver".

Insert USB-CMOS converter to the USB port of computer. Connect configuration cable to the "CONFIG CMOS" port on the module's front panel. Thus, the computer is connected with the module and ready for performing any changes in configuration (see figure 4 "Configuration via USB port of computer").

Figure 4: Configuration via USB port of computer

3.1.2 Using of „PuTTy" freeware program for configuration

The module configuration can be done with using of any suitable program for the serial line communication. The description bellow is relevant for the open-source software „PuTTY" that is available for free on www.putty.org.
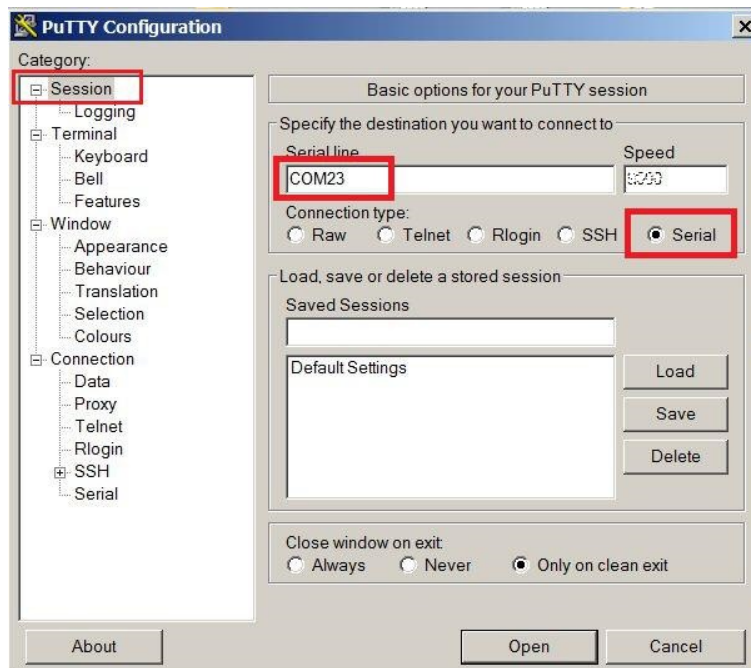
Figure 5: Terminal setting for serial line communication

„PuTTY" software runs after clicking on the downloaded file „putty.exe". There will open a window of the terminal communication (see Figure 5). For switching the program into the serial line communication, choose „Serial" option of the connection type in the „Session" tab.

Check (or set up) the communication speed („Speed") to 19200 bits/s and then enter into the „Serial line" tab the number of the serial port that the system automatically assigned to the virtual port at the moment of interconnection module to the computer. The number of the serial port can be found in OS Windows by using of „Device Manager" (Control Panel/System and Maintenance/Device manager) by clicking on „Ports (COM a LPT)" where the numbers of ports appear (e.g. „COM23" - see figure 3).

Click on „Open" button in „PuTTY" program and open the terminal window. After pressing of „ENTER" key there will appear a command prompt **„sj3"** which announces that the module is ready to be configured (see figure 6).
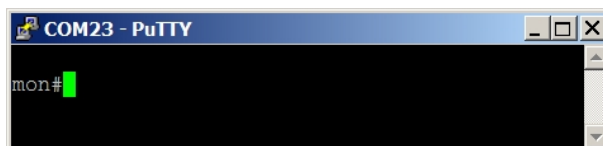
Figure 6: Open terminal window for module configuration via serial line

3.1.3 General rules for configuration of the module by configuration cable

Activate the terminal window for the configuration via the configuration cable according to the instructions above. These general rules are valid for entering commands into the command line:

- the command must be entered only when a prompt for command appears in front of the cursor mark (colored or flashing little square); the prompt is either „sj3" or „mon" format (see figure 6);
- it is possible to enter only one command each time;
- the command could be entered in an alphanumeric character (or several characters);
- the command is sent to device by clicking on „ENTER" key. After the command being carried out, the prompt will appear again and it is ready for a new command to be entered. In case the command fails to execute, there will appear an error report;
- check the execution of the command by displaying of the list of configuration parameters which appears by entering "show" or "/" and pressing on „ENTER" key;
- to display a summary of configuration commands and their parameters („HELP"), enter "?" (question mark), or "/?" and press „ENTER" key;
- when entering characters, distinguish strictly the capital and small letters (according to the documentation or „HELP");
- Do not enter other characters than those listed in „HELP" or in the documentation, otherwise you would be risking the unwanted command enter that might be the same as the ones used for manufacturer settings, diagnostics or service and repair.

3.2 Configuration of the module via radio

Remote configuration via radio signal is proceeded via special WACO radio messages (queries and commands) that will query the module to get current settings of its individual parameters, or (in case of need) will send a command to change these parameters.

It is possible to configure the module locally from the convenient spot within module radio range (for example from PC with connected gateway WM868-RFU - see figure 7), or to configure the module remotely from a remote computer via local gateway WM868-RFE (WACO Ethernet Gateway) or WM868-RFG (WACO GSM Gateway) as depicted in the figure 8.
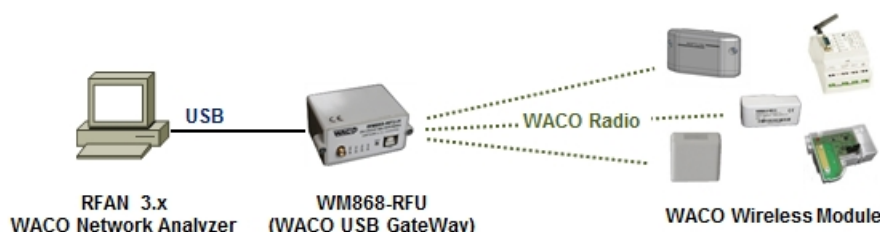
Figure 7: Principle of local configuration via radio

In both cases there must be direct radio visibility between the configured module and the communication gateway – it is totally **impossible to configure the WM868-SI2/SI2-H modules via repeater**.

3.2.1 Using of „RFAN 3.x" program for the module configuration via radio

The universal tool for the configuration of WACO family modules is „WACO Radiofrequency Analyzer RFAN 3.x" (hereinafter „analyzer") that can be used for setting up of all remotely configurable parameters of the module. Analyzer is a computer program written in Java language, which can be installed to any common PC (desktop, laptop, tablet...) with operating system with Java Virtual Machine support. Functionality of RFAN 3.x analyzer
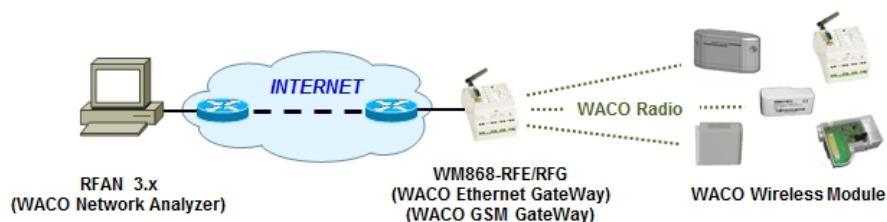
Figure 8: Principle of remote configuration via radio

is described in detail in the „WACO RFAN 3.x – Software description and configuration" manual, where there are also described in details the steps how to find out current setting of a particular parameter and how to change the setting.

Purpose and importance of all configuration parameters is described in the next part of the document. Overview of all parameters that can be configured via radio can be found in the section 3.6 „Setting of module parameters via radio". General principles and technique of radio configuration are described in details in section 3.2.3 „General rules of configuration via radio".

3.2.2   Connection of WACO communication GateWay to computer

WACO Communication Gateway is the device intended for communication among a WACO supported software application (e.g. RFAN 3.x) and all subordinate elements of WACO wireless network. The GateWay can be connected to the computer with the RFAN 3.x application directly (through a convenient port of PC) or indirectly through the IP network. „WACO USB GateWay" (with USB support) as well as „WACO Ethernet GateWay" (with etrhernet support) can be connected directly, while „WACO Ethernet GateWay", and „WACO GSM GateWay" can be connected indirectly, what means that the GateWay is not connected to the computer with analyzer, but it is connected to the remote Ethernet/IP port of the IP-network (Internet) anywhere over the world provided that there is an IP-connection between the computer and the GateWay (see figure 8).

Connect WM868-RFU (WACO USB GateWay) to the USB port of computer with RFAN 3.x program. The module is powered from the USB port of computer, so it automatically goes „on" and three virtual serial ports are activated: one for data connection, one for configuration and one for possible firmware upgrade. The device appears in the „Other devices" section of the „Device manager" window and its virtual serial ports appear in the „Ports (COM and LPT)" section as depicted in the figure 9.
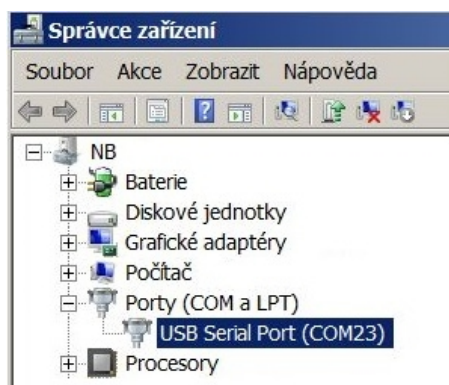
Figure 9: Appearance of WACO USB GateWay in the MS Windows „Device Manager"

If there is no appropriate driver with support of multiple virtual serial ports over USB installed in the computer, it is not possible to select serial port in RFAN 3.x setting (no serial port is available for choice). In this case the virtual serial ports appear in the „Other devices" section of „Device Manager" and it is necessary to install appropriate driver according to the instructions stated in part 3.4"„USB GateWay and USB-IRDA driver installation".

3.2.3   General rules for configuration via radio

RFAN 3.x Analyzer enables remote configuration of WACO radio devices. This function is accessible in folder „Remote Config". The principles of the configuration tools are following:

   - select the device to be configured (or read current configuration)

- select variable that should be changed (or read)

- launch function „GET" for reading current value, or „SET" for changing of value or „WALK" for reading of all values

When performing of configuration (i. e. making changes or just reading of current settings) keep these general rules:

1. the configuration cannot be made in bulk, there must be always only one device chosen that will be configured;

2. each single variable is set up/queried by a single command/query;

3. there is a possibility to define more configured/queried variables within the tool and run their configuration/query by one click as a sequence, nevertheless, the configuration/querying of each variable is processed individually, one after another, in the order in which the sequence was set up;

4. in case the „WALK" command for querying the current status of all module's variables is used, the analyzer starts dispatching queries that will ask the individual variables step by step;

5. when a „SET" command was sent to device, the device will proceed the command (or not – see rule 6. and 7.) and turns back a value that is really valid after the command execution;

6. if a „SET" command was sent to a variable, that is of „Read Only" character (for example type of the device, or serial number), then the device will not process the command and turns back current value of the variable;

7. if a „SET" command contains such value that is out of the defined range of values of the variable, or that has no sense, then the device either not process the command or change the variable to closest possible value. In any case, the device will send back the value which is really set after proceeding the command;

8. if a „GET"/„SET" command contains variable that is not implemented in the particular device (the device „doesn't recognize" the variable), then the device turns back „null" value which appears in the analyzer as not accomplished command/query.

3.2.4   Remote configuration with using of RFAN 3.x Analyzer in steps

The configuration could be performed in „Remote configuration" mode (fold „Remote Config"). Add the device that should be configured into the left section of the screen by using of „Add RF Address" option of the section context menu (displayed by right-click). The new „Add RF Address" window (form) will open, where there it is necessary to fill in:

- fill device RF address in hexadecimal format marked „0x" (for example „0xffffef6d")
- tick the „Wake On Radio" option for battery powered modules
- write any description into the „Description" field for better module recognition
- by clicking to „Add" button add the device into the configuration list.

Entering of a device into the „RF Address" window is depicted in the left part of the figure 10.

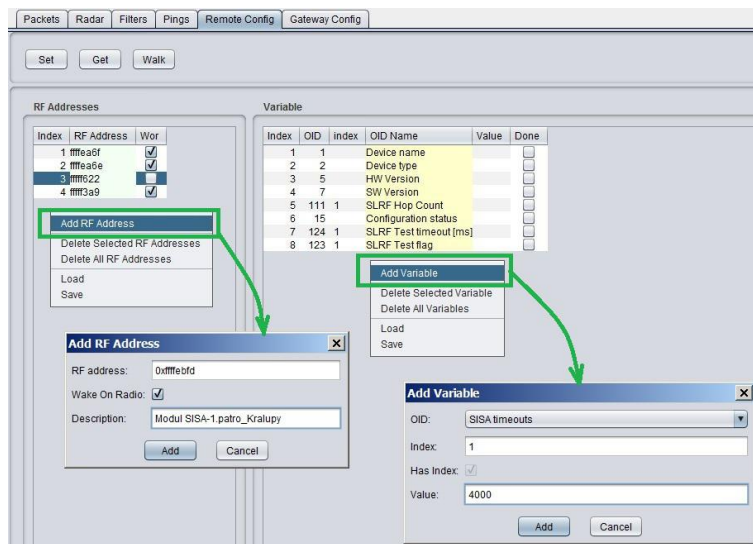Figure 10: Entering of devices and variables into the remote configuration window

Create the sequence of variables that should be configured (query or set) by clicking on „Add Variable" option in the right section context menu. The new „Add Variable" window (form) will open, where there it is necessary to edit following fields:

- into OID field (Object ID) select a name of variable that should be added in the sequence

- in case the variable has an index, put the index number in (information box „Has Index" is ticked and „Index" box is editable);
- set up required value of the variable into the „Value" field. If the variable will be just read (checked its current value), leave the field blank. Those variables, that have „Read only" status (invariable constants, measured values) will have the „Value" box uneditable;
- by clicking on „Add" button add a variable to the sequence of variables used for configuration.

Entering of a variable into the „Variables" window is depicted in the right part of the figure 10.

Command **GET** (reading the current variable value), **SET** (setting up the required variable value), or **WALK** (reading the current status of all variables) will be done only for one chosen device from the list of devices in **„RF Address"** tab. Run the required command by clicking on relevant button in the top of the screen. After the click, there will appear an information window in which a progress of getting/setting process of will be displayed. As the individual settings are performed, the „tick" symbols in the „Done" box appear item-by-item. The „Getting/Setting" window will disappear after the all commands of the sequence are being accomplished, or after the expiration of the preset time limit (TimeOut). The current variable values are listed in the field „Value" in the relevant row.

Figure 11: Progress of getting values of preselected variables of the module by using of „GET" command

To avoid serious mistakes that can bring the module into paralyzed condition, numb for further communication, it is necessary to know the meaning of all modified variables of the device, including their mutual relations.

Example: *If value of „SLRF Test Flag" variable is set to "1", the module will be preset to send test messages in period which is set up by variable „SLRF Test Timeout [ms]". In this case the period is just 1 millisecond. The trouble will occur if the test broadcasting would be switch on. It is necessary to set some reasonable period (e.g. 5 second) first and just then switch test broadcasting "on", otherwise the module would broadcast permanently and never be able to receive any other command.*

When configuring battery powered modules, always use the „Wake-On-Radio" (WOR) function. The function enables to „wake up" the module with a special „waking" radio signal from „hibernation" mode (that means the mode in which the module is almost permanently) to the mode of active signal reception. Keep in mind that by „waking up" of the particular required module the other modules, that are placed within the GateWay current radio range, will also be activated. Excessive activating of the module can cause the reduction of its battery life. To avoid the excessive „waking" of many modules around the GateWay it is recommended to follow these instructions:

- do not change the parameters if it is not necessary for the module's functionality;   - consider the succession of the configuration commands (or prepare them as a „template");   - do not use command „WALK" if not necessary - (reading of all module variables);   - find suitable place for the configuration, that is in a good reach of configured device.

We also recommend keeping the modules in closed boxes, shielded with aluminum foil (or in metal boxes) so the modules are protected from the excessive „waking up" and their batteries won't be damaged. When you do the preliminary configuration before mounting, always take out from the shielded box only the necessary number of modules. After their configuration, the modules should be placed back in the shielded box.

3.3   USB-CMOS converter driver installation

If the computer operation system failed in automatic installing of the driver for the „USB-CMOS", it is necessary to install the driver manually. The relevant current driver can be found on a chip manufacturer's (FTDI) webpages, namely in the „VCP Drivers" (Virtual COM Ports) section.

   www.ftdichip.com/Drivers/VCP.htm

In the „Currently Supported VCP Drivers" table find a link to a driver relevant to your operating system. To download the file, click on a link in the table. After downloading the file (in .ZIP format) into any directory in your computer, unzip the file. It will create a new folder (directory) with a set of files (e.g. „CDM 2.08.24 WHQL Certified").

Connect the converter „USB-CMOS" to your computer and open a „Device Manager" tool. The converter with the disabled driver will be displayed in the top right corner of the window as „Other Devices" (see figure 13 left).
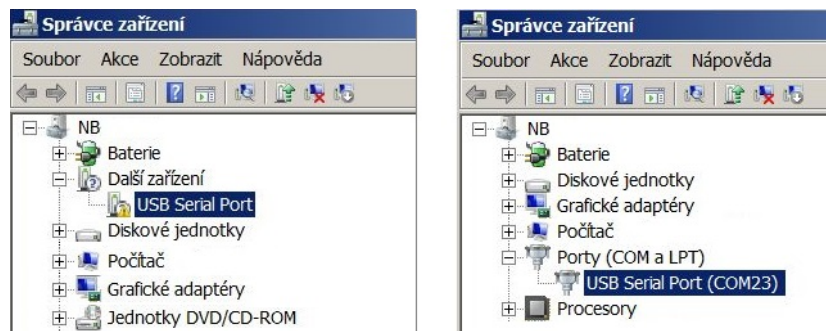
Figure 12: Appearance of converter without driver in the Windows „Device Manager" table

Click by right mouse button on „USB Serial Port" and choose „Update Driver Software" option in the context menu. Choose „Find Driver in this computer" option in the „Update Driver Software" window. Use „Browse" button to set up the path to the driver's folder (directory) and then click on the „Next" button. The driver installation process will launch. After the driver installation is completed, the standard „Installation Completed" message will appear. After the installation the converter will appear in the „Ports (COM and LPT)" section of the „Device Manager" window (see figure 13 right).

3.4   „USB GateWay" and „USB-IRDA" driver installation

The driver „ugw3.inf" intended for support of multiple virtual serial ports through the USB interface of a computer is a part of delivered installation pack. If your version of MS Windows operating system failed in automatic installation of a driver for connected „USB GateWay" or „USB-IRDA" device, make an installation of „ugw3.inf" driver manually.

Connect the device to computer and open a window of „Device Manager" tool. The device appears in the „Other device" section in upper part of the window as „USB Serial port" device (see figure 13 left).
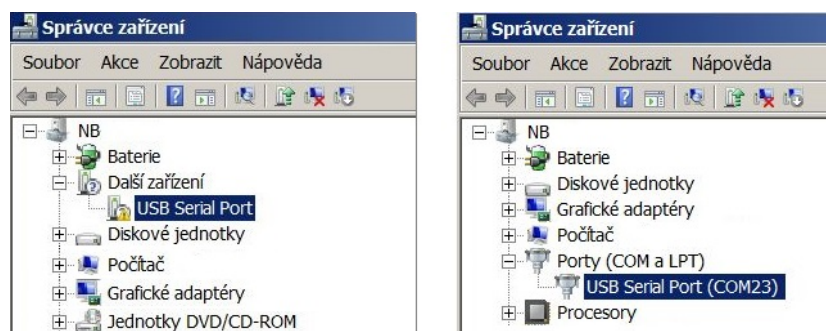
Figure 13: Displaying of the device without driver in "Device Manager" window

By right-clicking to „USB Serial port" open the context menu and choose „Update driver software" item. Click on „Find driver in this computer" in the opened window. Click to „Select driver from the list" and „Next" in next window. After a new „Select device type from the following list" window appears, select „Ports (CPM & LPT)" in the window and click to „Next" button (see figure 14 left). Choose „From disc" in the next „Choose driver which you want to install" window (figure 14 right).

After that a new „Find file" window appears. Set the folder with driver file in the „Browse" tool, select „ugw3.inf" file name that will appear in the window and click to „Open" button (see figure 15 left). A new „Choose driver to be installed for the hardware" window will appear, select „RFU Gateway Serial port" item and click to „Next" button (see figure 15 right).
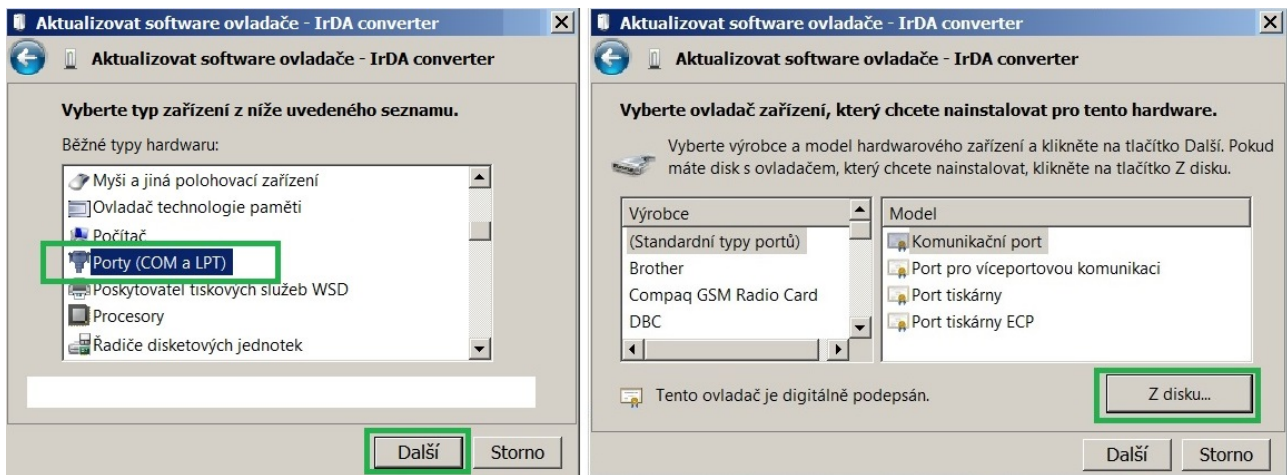
Figure 14: Manual selection of the driver file from a folder
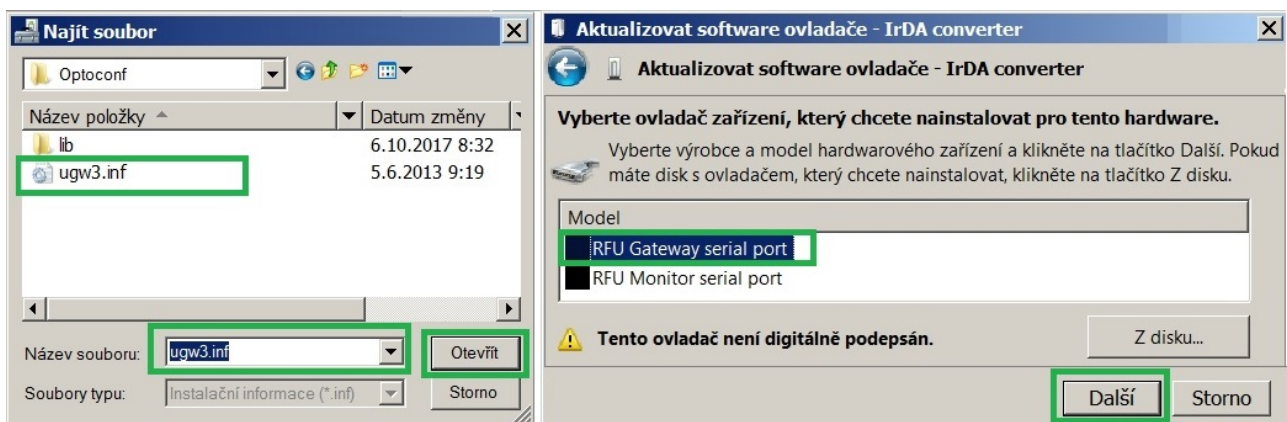
Figure 15: USB driver installation

A new „Driver software installation" window will appear with standard red „unknown driver producer" Windows system warning. Click to „Install the software anyway" option and the installation process will launch (*). After the process is completed the system shows positive message „The driver was successfully installed" (or similar). The device will move to the „Ports (COM & LPT)" section of the „Device Manager" window (see figure 13 right).

(*) If installing the driver into the Windows 8 or Windows 10 OS computer, it could be a security problem with the installation because the driver doesn't have a digital signature („unsigned driver"). In this case follow the instructions below.

3.4.1 How to disable driver signature enforcement in Windows 8 system

Enforcement of signed driver installation in Windows 8 can be disabled by following procedure:

- by pressing the „Windows + R" keys open the „Run" window;
- write a restart command "shutdown.exe /r /o /f /t 00" into the „Open" editable field;
- choose „Troubleshoot" option in the „Choose an option" window that will pop-up;
- choose „Advanced options" in opened „Troubleshoot" window;
- choose „Windows Startup Settings" in opened „Advanced options" window and run „Restart";
- during the system restart process a window „Advanced Boot Options" appears, choose „Disable Driver Signature Enforcement" option in this window;
- after launching the system install the driver according the above mentioned instructions.

Deactivation of the enforcement of signed driver function of the Windows 8 operating system is functional only until the next restart of the system.

3.4.2 How to disable driver signature enforcement in Windows 10 system

Enforcement of signed driver installation in Windows 10 can be switched-off by following procedure:

- click to „Windows" icon in left the bottom left corner of the screen and choose „Settings" icon;
- select „Update and security" in „Settings" window;
- select „Recovery" in next window';
- select „Advanced startup" section in „Recovery" window and click to „Restart" button in the section;
- in a few seconds the new „Choose an option" screen appears; select „Troubleshoot" option;
- in next steps select „Advanced options" and „Startup repair" options and click to „Restart" button;
- in this step an instruction for entering of „BitLocker" recovery key could appear (depends on the system settings). This is a 64-character access key for data section of the user that can be used in case of loss of OS Windows password. The key can be found in the „Microsoft Account Settings" page, that can be displayed by clicking to „Windows" icon and „User" item of main Windows menu. To get to the account it is necessary to click to „Change account setting" and „Manage my Microsoft account" and log into the account by using of Microsoft user login/password. Select „Device" in main menu of the user account page and click to „Obtain BitLocker recovery key" in „Desktop" section and „Bitlocker" subsection. The new screen with recovery keys will open. Copy down the key that is valid for the required unit (according to the required unit identifier);
- after entering of the key the new screen with startup options will appear, select „Disable Driver Signature Enforcement" option from the list. The selection can be done with using of F1 - F10 keys, for selected option with order number „7" press key „F7";
- after OS Windows restart perform the driver installation according to the above described procedure.

Deactivation of the enforcement of signed driver function of the Windows 10 operating system is functional only until the next restart of the system.

3.4.3 Support of older OS Windows versions and OS Linux support

Earlier MS Windows versions (Vista, Windows XP and older ones) do not support sufficiently the installation of multiple virtual serial ports onto one physical USB port and the current versions of „USB GateWay" and „USB-IRDA" devices cannot be connected to the computers with these operating systems.

There is no need to install any drivers with serial port support to the computer with Linux OS as the Linux system will automatically use its own generic drivers.

3.5 Setting of WM868-SJ-MS module parameters by configuration cable

In following part of the document there is a description of these parameters of the WM868-SJ-MS module, that can be displayed and examined from PC connected to the module by configuration cable. Some of the parameters can be changed by configuration commands entered „from the console" as described in paragraph 3.1.

3.5.1 List of WM868-SJ-MS module configuration parameters

List of all configuration parameters of the module can be displayed by entering of "/" (slash) command and pressing of „ENTER" key. The following list of parameters will display in the terminal window:

```
sj3>/
CONFIGURATION: OK
RF Address: 0xFFFEE009
hop count: 3
group: 0
SLRF flags: e
test timeout: 2
TX Power: 80
channel: 0
RX timeout: 1
RF Driver flags: C
Crypt Keys for:
Run test: 0
Debug level: 0
Baud: 2400
Parity: Even
Stop bits: 1
Data bits: 8
TX On     timeout: 0 usec.
TX Off    timeout: 0 usec.
Interbyte timeout: 10 ms
Idx Addr ID       Manuf  Medium Version Fabrication
-----------------------------------------------------------------------
sj3>
```

Overview of configuration parameters with short description of their meaning can be also found in table 2 on the page 23. The detailed description of individual parameters and their setting possibilities can be found in the following part of chapter 3.5.

3.5.2 List of all configuration commands ("HELP")

List of all configuration commands ("HELP") can be displayed by entering of **"/?"** command into the command line and pressing of „ENTER" key. The following list of commands will display in the terminal window:

```
sj3>/?
/W - write configuration
/# - erase configuration
/x - RESET
/@@@ RF address - (in hexadecimal)
/h number - hop count (0-15)
/g number - group address (0-65535)
/f[+-] flags - e-extender, Z-AZRA algorithm
/T number - test timeout (in 1/20 sec.)
/P number - TX power in dBm
/c number - channel
/X time - RX timeout (50ms)
/F[+-] flags - C-CD detect, R-RX only, W-WOR active, G-high gain
/!!! (f freq_in_khz | freq_const)
/K port d - delete key
 port key- add/change key

/E number - run test
/w - send empty WOR packet
/D number - debug level
/b baud    - set baud rate (300..115200)
/p [n|e|o]   - set parity (none,even,odd)
/s number   - set stop bits (1,2)
/d number   - set data bits (7,8)
/O timeout  - set TX On timeout in usec
/F timeout  - set TX Off timeout in usec
/i timeout  - set interbyte timeout in ms
/M index d    delete MBUS device
/M index primary ID/secondary manuf medium version  [fabrication]
sj3>
```

Exact meaning and using of individual commands is explained in details in the following part of chapter 3.5.

3.5.3 „Configuration" group of commands for writing of configuration and reset

The module contains two sets of configuration: operating configuration and saved configuration. At the start of the system the module copies saved configuration into the operating configuration, with which continues to work. If the user changes configuration parameters, it does so only in operating configuration.

Current status of storing of configuration parameters can be displayed in the list of all configuration parameters as „CONFIGURATION" item:

```
CONFIGURATION: OK
```

Information **„OK"** means, that the operating configuration is stored (it is identical with stored configuration)

Information **„NOT WRITTEN"** means, that the operating configuration is different from the configuration stored in Flash.

Configuration **can be saved** to Flash memory by using of **"/W"** command. Example:

```
sj3>/W
```

If the current operating configuration was not stored to FLASH memory, the module returns to the saved configuration after reset. If the parameter should be changed only temporarily (for example switch-on „test" function during diagnostics), it is not necessary to save operating configuration into FLASH memory (after diagnostics the function will be switched-off anyway). If the parameter should be changed permanently, there is necessary to save the configuration to FLASH memory.

Configuration can be **erased from the Flash memory** by using of **"/#"** command. Example:

```
sj3>#
```

WARNING! This command is recommended to use only by users with good knowledge of the system, or after consultation with the manufacturer.

The **module reset** can be performed by using of **"/x"** command. Example:

```
sj3>/x
```

After entering the command the module goes to software restart.

Change of some configuration parameters has an effect only after module reset (e.g. retuning of module radio by changing of „SLRF Channel" parameter). In this case it is recommended to create a configuration sequence containing commands for change of parameter, saving the change to Flash, as well as command for performing of module reset (..and exactly in this order).

3.5.4 Commands for settings of radio-frequency subsystem

This group of commands enables setting of transmitting, receiving, repeating and addressing system. There are following commands:

/c number	*frequency channel setting (SLRF Channel)*
/h count	*maximum number of re-transmissions (SLRF Hop Count)*
/f[+-] flags	*repeating mode setting (SLRF Repeater flag)*
/F[+-] flags	*transceiver mode setting (RF Driver flags)*
/X time	*receiving time interval (not used)*

Names of parameters that are configured by individual commands are stated in the brackets.

The **„SLRF Channel"** parameter is a number of module frequency channel. RF modules of WACO communication system can be tuned to any of three separate frequency channels that don't influence each other.

Frequency channel of the module can be set by **"/c [number]"** command, where value 0, 1, or 2 means number of frequency channel to be tuned. Change of frequency channel is effective only after module reset. Example of sequence of commands for module setting to the frequency channel "1":

```
sj3>/c 1
sj3>/W
sj3>/x
```

The **„SLRF Hop Count"** parameter is a maximum number of re-transmissions of the messages, broadcasted by the module. If, as an example, the parameter is set to value "3", each message originated by the module will be discarded after three re-transmissions (it is repeated no more than 3 times). This mechanism prevents the system from uncontrolled circulation of the message within the network. It is recommended to set the parameter to "n" or n+1" value, where "n" is the least number of re-transmissions which is necessary to get the massage to its destination. If the „SLRF Hop Count" value is too low, the message is discarded before reaching of its destination. If the „SLRF Hop Count" value is too high, capacity of the network is loaded by useless repeating of the messages.

The „SLRF Hop Count" parameter can be set by **"/h [number]"** command, where the value from 0 - 15 interval means the maximum number of re-transmissions ("hops") of the messages, broadcasted by the module. Example of command for setting of „SLRF Hop Count" parameter to value of 3 "hops":

```
sj3>/h 3
```

The **„SLRF Repeater flags"** parameter is intended for setting of repeating (re-transmission) mode. Repeating mode can be set by using of **"/f[+-] [flags]"** command, where the required mode is chosen by entering of one of following pre-defined symbols („flags"):
- value **" "** (without flag) - none of below mentioned functions is involved
- value **"e"** - setting of basic repeating mode (without back transfer suppression)
- hodnota **"Z"** - setting of advanced repeating mode with back transfer suppression (AZRA)

- value **"m"** - designating of the module as a „Master" of virtual bus

Example of command for setting of the module as a repeater with „Advanced repeating mode AZRA" (recommended setting):

```
sj3>/f e Z
```

The **"RF Driver flags"** parameter is intended for setting of module transceiver mode. The mode can be set by using of **"/F[+-] [flags]"** command, where the required transceiver mode is chosen by entering of one or more of following pre-defined symbols („flags"):

- value **"C"** - full anti-collision protection (carrier and frame transmission detect) enabled
- value **"R"** - limited anti-collision protection (carrier detect) enabled
- hodnota **"W"** - „Wake On Radio" (WOR) function of the receiver enabled
- hodnota **"G"** - „High Gain" function enabled (it has no effect for WM868-SJ-MS module)

Important notice:

The **"C"** and **"R"** functions are alternative options and their setting works as a **change-over switch** (when one of them is enabled, second one is automatically switched off). The **"W"** and **"G"** functions are independent. Their flags can be added or removed **individually** by using of +/- symbol before the flag.

Example of command for common setting of „Full anti-collision protection" and „Wake On Radio" functions and corresponding record in the module configuration summary:

```
RF Driver flags:  R
sj3>/F C +W
RF Driver flags:  CW
```

Example of command for switching of protection to „Limited anti-collision protection" mode and corresponding record in the module configuration summary:

```
RF Driver flags:  CW
sj3>/F R
RF Driver flags:  RW
```

As seen in the example, by enabling of "R" function the original "C" function was automatically switched off and it had no influence on the "W" function.

Example of disabling of "W" function and corresponding record in the module configuration summary:

```
RF Driver flags:  RW
sj3>/F -W
RF Driver flags:  R
```

As seen in the example, disabling of "W" function had no influence on the "R" function.

Example of command for common setting of "W" and "G" functions and corresponding record in the module configuration summary:

```
RF Driver flags:  R
sj3>/F +W +G
RF Driver flags:  RWG
```

Example of command for switching of anti-collision protection to "C" mode together with disabling of "G" function and corresponding record in the module configuration summary:

```
RF Driver flags:  RWG
sj3>/F C -G
RF Driver flags:  CW
```

*When the **„Full anti-collision protection"** function is switched on, the module opens its receiver for an instant before broadcasting and „listens" whether the frequency channel is clear. If a carrier frequency is detected or transmission of a frame is underway, the module postpones broadcasting of the message for a moment and then tries again. This procedure protects transmission of the message from interference with disturbing signal on the same frequency as well as from collision with broadcasting of other modules.*

When the **„Limited anti-collision protection"** function is switched on, the module goes to transmission if there is no other frame underway (but, unlike the full protection, detection of carrier is not performed). This procedure does not protect broadcasting against disturbing signal, but protects transmission of the message from collision with broadcasting of other modules. This setting is recommended in this case when the module works in the environment with permanent disturbance of carrier frequency and it has no sense to waste time (and battery power) by waiting for clear channel.

When the „**Wake On Radio**" (WOR) function is enabled, the module can be anytime remotely activated from hibernated state. As the WM868-SJ-MS module is permanently active, this function has no importance and should be switched off.

The „**/X**" command is intended for setting of „receiving time interval", what is the interval immediately after sending a message in which the module's receiver is active. The interval is set in „system units" of 50 ms (20 units = 1 second). As the WM868-SJ-MS module's receiver is permanently active, this function has no importance.

Important note! Even the possibilities of transceiver settings are identical for all modifications of the WM868-SJ-MS module, older versions of the module can have a **different way of choosing of the required transceiver mode**. In this manner the switching of transceiver mode should be performed by using of "**/f[+-]**" command (the same as for setting of repeating mode), where the set of flags is supplemented with following flags for seting of transceiver mode:

- flag **"C"** for full anti-collision protection setting (Carrier Detect)
- falg **"w"** for enabling of „Wake On Radio" (WOR) function
- flag **"G"** for switching of „High Gain" function (not used)

Switching to limited anti-collision protection mode can be performed by removal of "C" flag from the configuration.

Switching from factory preset full anti-collision protection mode to the limited anti-collision protection mode can be performed this way:

```
SLRF flags:  eCz
sj3>//f -C
...  SLRF flags:  ez
```

Manner of transceiver settings control of the particular device is obvious from the summary of configuration commands („HELP"), that can be displayed by "**/?**" command. The **„SLRF Group Address"** parameter can be used for setting of module group address. Practically unlimited number (65536) of groups can be created within each WACO RF network and these addresses can be also used for addressing (besides individual addresses). If a group address is used, the message is delivered to all modules of that group. As all currently produced battery powered modules use „broadcast" type of addressing, setting of group address into the WM868-SJ-MS is not required. But it is possible, that some of the module future applications will use group addressing.

Setting of **module group address** („SLRF Group Address") can be performed by using of "**/g [number]**" command, where the number from 0 - 65535 interval is the module group address. Example of setting of the group address to the "21" value and corresponding record in the module configuration summary:

```
sj3>/g 21
...
group:  21
```

3.5.5   Commands for setting of M-Bus Slave interface

This group of commands is intended for setting of M-Bus Slave data bus parameters that is used for communication with connected M-Bus master. There are following commands:

/b baud	*setting of data-bus bit speed (300 - 9600)*
/p [n/e/o]	*setting of data transfer parity (none,even,odd)*
/s number	*setting of stop-bit number (1 or 2)*
/d number	*setting of data-bit number (7 or 8)*
/i timeout	*setting of interbyte timeout in ms*

The "**/b [baud]**" command can be used for setting of **bit transfer speed** („communication speed") on the serial/bus interface. The speed must be adjusted to the value, that is suitable for connected meters. Setting will be effective only after module restart. Example of setting of the communication speed to "9600" baud value:

```
sj3>/b 9600
```

The **"/p"** command can be used for setting of **parity bit** of the serial/bus interface. There are five options of parity bit setting:

- value **"n"** means "none parity" (none)
- value **"e"** means "even parity" (even)
- value **"o"** means "odd parity" (odd)

Example of setting of the parity bit to "even":

```
sj3>/p e
```

The **"/d"** command can be used for setting of **number of data bits** of the serial/bus interface, where the number "7" or "8" can be used. Example of setting of the number of data bits to "8" value:

```
sj3>/d 8
```

The **"/s"** command can be used for setting of **number of stop-bits** of the serial/bus interface, where "1" or "2" value can be used. Example of setting of the number of stop-bits to "1" value:

```
sj3>/s 1
```

The **"/i"** command can be used for setting of **interbyte timeout** of the serial/bus interface. The module gradually (one-by-one) stores incoming Bytes from serial interface into radio-packets and (when the packet is loaded) sends the packets through RF interface to other module. If there is a "silence" after last received Byte longer than interbyte timeout, data sequence is considered as complete (no more data are expected) and radio-packed is transmitted, even if it is not fully loaded. As in current "collection unit" application the module of WM868-SJ-MS type does not transmit RF-messages, this setting is not important for the module. But it is possible that some of the module future applications will require setting of this parameter.

Example of setting of interbyte timeout to "10 milliseconds" value:

```
sj3>/i 10
```

Setting of all serial interface parameters is stated in the list of all configuration parameters in following rows:

```
Baud:  9600
Parity:  Even
Stop bits:  1
Data bits:  8
Interbyte timeout:  10 ms
```

3.5.6   Setting of "Table of virtual M-Bus devices"

The WM868-SJ-MS module basic function (described in paragraph 1.2 "Module usage") is supported by "Table of virtual M-Bus devices", stored in the module memory. This table contains records of all WACO devices and their variables alongside with the identification of these devices and variables in M-Bus system. This table serves for transformation of messages, obtained in the original WACO format, to the M-Bus standard format supported by bus control unit (M-Bus Master).

The "Table of virtual M-Bus devices" can be browsed by entering of **"/M"**. command. The table with configured data looks as following example:

```
Idx Addr ID        Manuf   Medium Version Fabrication
----------------------------------------------------------------------
  1   23 12345678 SFT        7       1 sn000021
    0 - DIF:04    VIF:13       0xFFF512A7  100/1   3600            0
    1 - DIF:04    VIF:13       0xFFF512A7  100/2   3600            0
  2   24 12312345 SFT        7       1 sn000076
    0 - DIF:04    VIF:13       0xFFF512BA  100/1   3600            0
  3   25 12312378 SFT        7       1 sn000129
    0 - DIF:04    VIF:13       0xFFF512C1  100/1   3600            0
```

As evident form the example of statement above, the table consists of **basic** (primary) „rows of virtual M-Bus devices" (row number 1, 2 and 3) and **nested** „rows of M-Bus variables" (indented rows with indexes "0 -" and "1 -"). Basic table of M-Bus devices contains columns, that match with the descriptions in the table header and have following meaning:

- value **„Idx"** - row index (order number)
- value **„Addr"** - M-Bus standard primary address
- value **„ID"** - M-Bus standard secondary address
- value **„Manuf"** - M-Bus standard manufacturer code
- value **„Medium"** - M-Bus standard medium code
- value **„Version"** - M-Bus standard addressing version
- value **„Fabrication"** - optional serial number of meter/sensor

Each **basic row** of the "Table of virtual M-Bus devices" carries information about one **virtual M-Bus device**, registered in the M-Bus data bus. From M-Bus Master's point of view the virtual device behaves same way as any real M-Bus standard device on the bus - it has its primary and secondary address, serial number, manufacturer, medium... When the master requests current status of its variables, the WM868-SJ-MS module responds to the request as „agent" of virtual device, sending back standard M-Bus message, that carries above described identificattion and information entries (as described in details in chapter 3.7 „Structure of module data messages") and requested values of variables.

Each **nested row** contains **description of variables**, that are associated with the virtual device (...and will be transferred as its variables), together with definition of their real „source" (i.e. from which real WACO reading module the value is obtained). Each nested row carries following information:

- value **„Index"** - variable order number (assigned by system)
- value **„DIF"** - M-Bus standard variable DIF setting
- value **„VIF"** - M-Bus standard variable VIF setting
- value **„RF-address"** - RF-address of source WACO RF-module
- value **„OID/index"** - variable identifier in WACO NEP coding
- value **„Timeout"** - value obsolescence timeout (period of validity)
- value **„Value"** - last received value of variable

If there is one nested row under basic row of virtual M-Bus device, one variable will be read for this device (see rows with index 2 and 3). If there are several nested rows under one basic row, more variables will be read for that virtual device (see row with index 1).

Example: *The first virtual device in the table has primary address "23" and secondary address "12345678". It represents device with manufacturer code "SFT" (Softlink), that measures water (media code 07 = "Water"), its addressing version is "1" and serial number is "sn000021".*

The virtual device reads two variables, both of them have DIF values set to "04" (storage="0", data character=„current value", data format="32-bit integer") and both of them have VIF value set to "13" (variable type="volume", variable unit="0,001 m^3"). Both variables are read through the WACO reading module with RF-address of "FFF512A7", where variable OID-code is "100" ("Input value"). The first variable is read from the port number "1", second one is read from port number "2". Obsolescence period of both variables is set to 3600 seconds (1 hour).

Editing of M-Bus virtual device (i.e. „basic row" of the table) can be performed by using of following command:

"/M [index] [M-Bus ID] [M-Bus second. ID] [Manufacturer] [Medium] [Version] [Fabrication]

Example of addition of a „virtual M-Bus device" into the table (editing new basic row):

```
sj3>/M 1 23 12345678 SFT 7 1 sn000021
```

By using of this command the following new row will be entered into the table—:

```
sj3>/M
Idx Addr ID       Manuf  Medium Version Fabrication
-------------------------------------------------------------------
  1   23 12345678 SFT         7       1 sn000021
sj3>
```

Value **„Primary M-Bus address"** is „bus" address of connected meter according to the M-Bus standard. Entered address number must be unique within the bus and must belong to the 0 to 255 range.

Values **„Secondary M-Bus address", „Manufacturer", „Version"** and **„Medium"** are four components of device identification within the M-Bus standard. This combination must be unambiguous that means there cannot

exist two M-Bus devices worldwide, that have the same combination of all these parameters. If fixed configuration of the address components used, producer of the device is responsible for unique setting of „read only" address components for each device. If M-Bus address components are configurable, operator of the M-Bus system can use serial number of connected meter in combining with its type, subtype and manufacturer. Using of „independent" addressing line is possible only in that case, if the operator of the system owns its M-Bus manufacturer code and can assure that the identification of all operated devices under his code will be unique.

The **„Fabrication"** value is a serial number of the meter/sensor. This value is optional. If this parameter is entered into the table, the additional variable "Fabrication No" (VIF=78) will appear in the M-Bus message. If the parameter is not entered, "Fabrication No" variable will not be included into the message.

Editing of variable definition row (i.e. „nested row" of the table) can be performed by using of following command:

"/M index v [timeout] [RF-address] [OID/index] [DIF] [VIF]"

Example of addition of a „variable definition" to the record of M-Bus virtual device with index "1":

```
sj3> /M 1 v 3600 0xfff512a7 100/1 0x04 0x13
```

By using of this command a new variable with index "0" was attached to the virtual M-Bus device with index "1". It can be seen in the table as „nested" row under basic row of virtual device:

```
sj3>/M
Idx Addr ID        Manuf  Medium Version Fabrication
--------------------------------------------------------------------
  1   23 12345678 SFT        7        1 sn000021
    0 - DIF:04    VIF:13        0xFFF512A7  100/1   3600             0
sj3>
```

The **DIF** code describes character of the variable, number of "storage" and format of data field according to the M-Bus standard.

Example: DIF="12" means value from "storage" number "0", variable is of „maximum value" character and it is in "16-bit integer" format

The **VIF** code describes the kind of measured quantity (e.g. volume, temperature, voltage...) and the measuring unit (including multiplier) in which the value is presented (e.g. m^3, °C, mV, kWh...) according to the M-Bus standard.

*Example: VIF = "06" means quantity of „Energy" type, measured in 10^3 * Wh = kWh units.*

The **RF-address** value is an unique identifier of that WACO RF-module, from which the variable is received. WACO collecting unit typically receives data from many WACO-system reading modules and attaches the values to the records of virtual M-Bus devices according to the „nested rows" configuration.

The DIF, VIF and RF-address values must be entered in **hexadecimal number** format ("0x[0 - F]").

Couple of **ID/Index** values determines which variable from incoming message of WACO reading module is selected as variable of given virtual device. The WACO reading module broadcasts in its message set of variables, that are assigned by "OID" (variable type) and "index" (port number) values. OID values that are used in a specific type of WACO module are described in the module documentation. List of all OID values with a short description can be obtained from the producer upon request.

The **"Timeout"** parameter is an „obsolescence period" of stored values of individual variables. If, in the moment of master's request, the stored value is older than preset "timeout", the value is considered as obsolete and "not known" value is inserted into the answering M-Bus message

By using of **"/M index d"** command any row with entered "index" can be **removed** from the „Table of virtual M-Bus devices". Required row will be irretrievably deleted from the table, including setting of all its variables.

After editing of the table of virtual M-Bus devices **store the table** by using of **"/W"** command.

3.5.7 Setting of test broadcasting

These commands can be used for setting of **test broadcasting function** of the module, that can be used for evaluation of radio signal in the installation site. When this function is switched on, the module broadcasts test messages in regular intervals and a quality of their reception can be evaluated around the module with using of WACO RF analyzer or any similar device.

The **"/T"** command can be used for setting of **period of the test broadcasting**. Length of the period is entered in „system units", where the value of one system unit is 50 ms (value of „100 units" means 5 second period). Example of setting of the testing period to 10 second (200 system units):

```
sj3>/T 200
```

By using of the **"/E [0/1]"** command the function of **test broadcasting can be switched "on" and "off"**. Test broadcasting is switched on with using of "/E 1" command, and it is disabled by using of "/E 0" command. Example of test broadcasting switching "on" command:

```
sj3>/E 1
```

WARNING! *Do not set "T" parameter to less than "50" value, otherwise the module buffers could be overloaded.*

3.5.8 Special commands for module activation and diagnostics

This group of commands is intended for the module initial setting during the manufacturing process, and for module diagnostics by manufacturer. It is strongly recommended using of these commands only by users with a very good knowledge of the system, or only after consulting with manufacturer. There are following commands:

/@@@ RF address	*insertion of module RF address (it can be done only once, not editable)*
/K port key	*insertion of AS128 encryption key for the particular application („port")**
/K port d	*removal of AS128 encryption key for the particular application („port")**
/P number	*transmitting power setting (Do not use! Only for factory setting!)*
/!!! f num.	*correction constant setting (Do not use! Only for factory setting!)*
/w	*send empty WOR packet (Do not use! Only for factory setting!)*
/D number	*„debug" statement switch-on (Do not use! Only for factory setting!)*

* none of the WM868-SJ-MS module applications currently use the data encryption with AS128 key

3.5.9 Module current status statement

The **module current status statement** can be displayed by entering of **"i"** command (without „slash") into the command line and pressing of „ENTER" key. Following statement will appear in the terminal window:

```
sj3>i
WM868-SJ-MS-LP-H   HW 1.33  SW: 6.0
8:0:0  14.10.2016  Reset cause=00000000 Uptime=11720
Config size: 2480
sj3>
```

In the first row of the statement there are basic information about the module type/subtype: **device name**, **hardware version/revision** and **software version/revision**.

In the second row there are values of **Systime, Reset cause** and **Uptime** parameters.

In the third row there are statuses and statements of some program sections (they could vary for different module modifications), that can be used only for module diagnostics.

The **„Systime"** parameter value shows setting of module real time. System time is kept in the same format as in computer operating systems, i.e. in seconds, starting from 1.1.1970 („UNIX Epoch time"). In default status (after battery switch-on) there is zero value in the counter and it increases by one every second. The module can be synchronized with the real time only via radio, by using of the **"SET"** command of the WACO RFAN analyzer (see paragraph 3.6). Setting of this parameter is not required for any common application of the module.

The **„Uptime"** parameter value shows the time interval passed from the last device reset in seconds so that the exact moment of the last module reset can be recognized by this parameter. The parameter is of „read only" type.

The **„Reset cause"** parameter value gives an information about the last reset circumstances. Following reset codes are relevant for this type of device:

- **„0"** means „Cold start" (caused by user „RESET" command)
- **„1"** means „Warm start" (based on „suspension" cause
- **„2"** means „Watchdog reset" (reset by „watchdog" system)

- **„3"** means „Error reset" (incorrect instruction or inconsistent data)
- **„4"** means „Power reset" (caused by low power voltage)

The parameter has „read only" character and it is used mainly for the diagnostics.

3.6 Setting of WM868-SJ-MS module parameters via radio

Almost all parameters described in paragraph 3.5 „Setting of WM868-SJ-MS module parameters by configuration cable" can be set alternatively via radio, with using of "WACO Radio-Frequency Analyzer RFAN 3.x". The only exception is editing of „Table of virtual M-Bus devices", that can be done only by configuration cablle. As this table is quite essential for the module functionality, it can be assumed that all the configuration will be performed mostly by configuration cable. This way of configuration is more convenient for the module, because the configuration connector is easily accessible, and the configuration is quick and simple.

General description of configuration via radio can be found in section 3.2 „Configuration of the module via radio", where there are explained relevant general rules as well as working procedure in steps.

The only parameter of the WM868-SJ-MS module, that can be set **only via radio**, is module **System Time**. However, this setting is not required for any common application of the module.

The module can be synchronized with real time by using of **"SET"** command. Open the **"Add variable"** form, select **"Systime (s)"** variable in "OID" field, and set current time in **"UNIX time"** format into the **"Value"** field as described in figure 16.
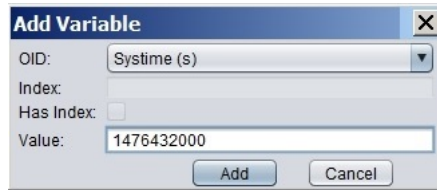

Figure 16: Setting of module System time via radio

List of all variables of the WM868-SJ-MS module that are accessible via radio, as displayed by the RFAN 3.x analyzer after using of „WALK" command, is shown in the figure 17.

Figure 17: Table of all WM868-SJ-MS module variables displayed by RFAN 3.x analyzer

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3.6.1 Overview of module configuration parameters

Overview of configuration parameters that can be used for user settings of the WM868-SJ-MS module is shown in the Table 2 below. The parameters are presented in the same order as they appear in the List of configuration parameters (see paragraph 3.5.1).

In the **„Value"** column there is a recommended range of setting of the particular parameter. If there is a „Code" indication in this column, it means that the value is shown in form of hexadecimal code, where couple of hexadecimal characters represents one Byte.

In the **„Default"** column there are default (factory) settings of the parameter. Colour marking of this field has following meaning:

- green colour - commonly used parameters that should be set in reliance on the specific usage
- red colour - parameters that are not recommended to change
- grey colour - values that cannot be changed („read only")

Table 2: Overview of WM868-SJ-MS module configuration parameters

Item	Name	Value	Description	Default.
1	CONFIGURATION	status	Configuration saving status	read only
2	RF Address	code	Module unique WACO RF-address	read only
3	Hop Count	0 - 15	Maximum number of message repeatings	3
4	Group	0 - 65535	Module group (multicast) RF-address	0
5	SLRF Flags	e, Z	Switching of repeater mode	
6	Test Timeout	20	Period of test broadcasting	1
7	TX Power	0 - 80	Transmitting power in dBm	80
8	Channel	0 - 2	Frequency channel number	0
9	RX driver flags	C, R	Switching of transceiver mode	C
10	Crypt keys	code	Encryption key	-
11	Run test	0 / 1	Switching of test broadcasting	0
12	Debug Level	code	Switching of debug logging level	
13	Baud	300 - 9600	Serial line transmission speed	2400
14	Parity	code	Serial line setting (parity)	even
15	Stop bits	1, 2	Serial line setting (stop bits)	1
16	Data bits	7, 8	Serial line setting (data bits)	8
17	Interbyte Timeout	1000	Serial line setting (Interbyte timeout)	10
Virtual M-Bus device parameters				
1	Index	Number	Virtual device index number	
2	Address	0-255	Primary M-Bus address	
3	ID	0 - 99999999	M-Bus ID (secondary address)	
4	Manufacturer	code	M-Bus „Manufacturer" code	
5	Medium	code	M-Bus „Medium" code	
6	Version	code	M-Bus „Version" code)	
7	Fabrication	text	Device serial number	
Parameters of virtual device variable				
1	Index	number	Variable index (order number)	read only
2	VIF	code	M-Bus VIF code	
3	DIF	code	M-Bus DIF code	
4	Timeout	number	Variable validity time-out	

3.7 Structure of module data messages

On the M-Bus Master's demand the WM868-SJ-MS module transmits into the data bus information messages with read data on behalf of all virtual M-Bus devices, that are listed in its „Table of virtual M-Bus devices". Each virtual device represents real meter/sensor connected to the WACO RF-network, which is not equipped with M-Bus interface (...and cannot be connected directly into the M-Bus interface). The WACO collecting unit assembles information messages in M-Bus format instead of such device, using static entries from the „Table of virtual M-Bus devices", as well as changing „useful data" (real variables) from individual meters/sensors obtained through the WACO RF-network. Principle of message conversion (transformation) from WACO format to M-Bus format is explained in the figure 18.
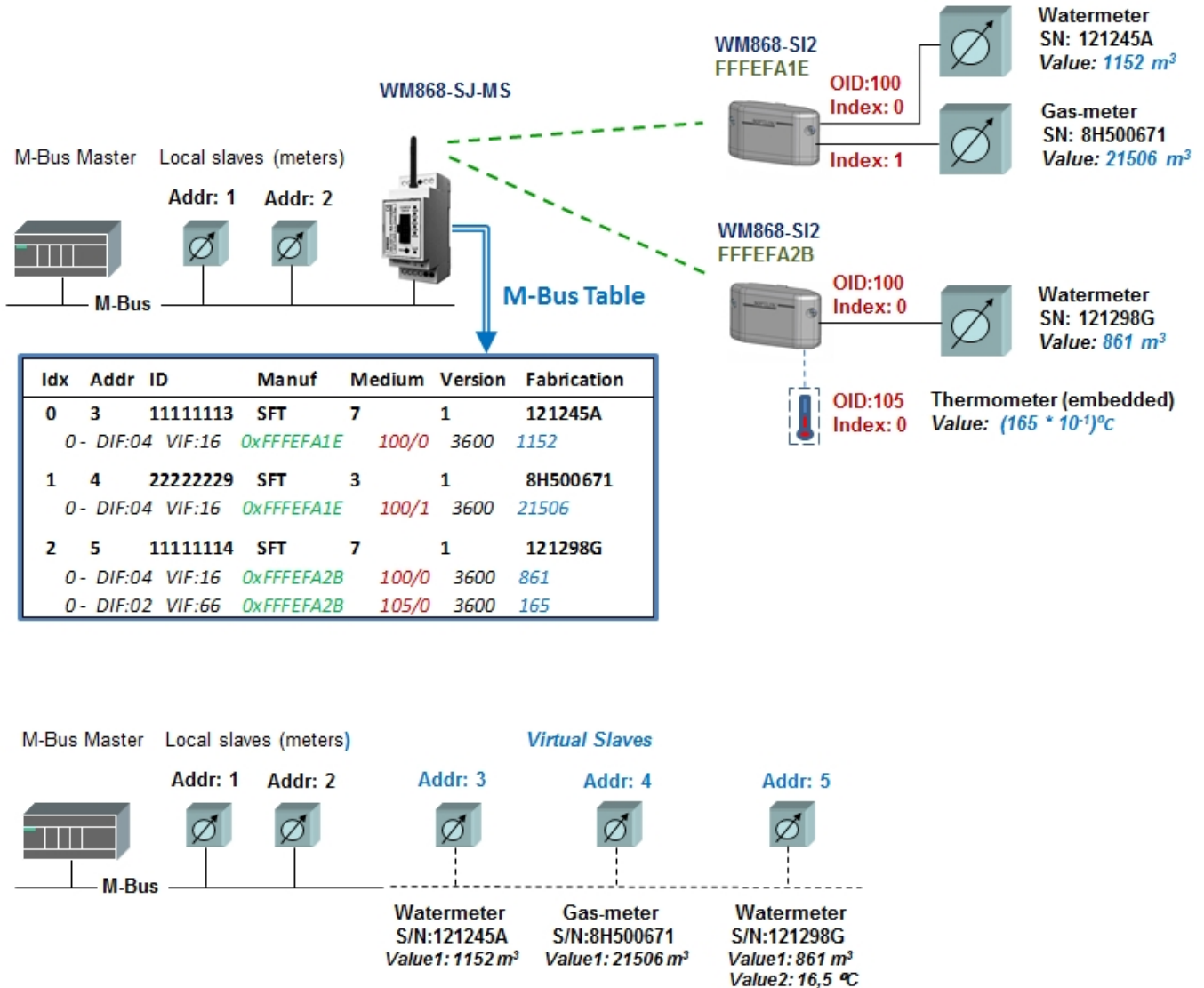
Figure 18: Principle of data conversion in WACO collecting unit

In upper part of the figure there is a set of M-Bus data bus comprised of M-Bus control unit (M-Bus Master), two local M-Bus slave devices (with primary address "1" and "2") and a WM868-SJ-MS WACO collecting unit, that acts as a „deputy" of three meters (water meter S/N "121245A", gas-meter S/N "8H500671" and water meter S/N "121298G"), that are connected through appropriate reading modules of WACO RF-network.

In „Table of virtual M-Bus devices" (M-Bus Table) there are created three records of virtual M-Bus devices (primary address "3", "4" and "5" - one for each real meter), together with „mapping" of individual variables from WACO system to M-Bus system. The first two devices are connected to the WACO RF-network through the same WACO RF-module ("FFFEFA1E"), where each virtual device has „its own" variable (100/0 and 100/1). The third virtual device has its own reading module ("FFFEFA2B"), and besides variable of „counter value" type (OID=100) there is also "temperature value" (OID=105), that is measured by reading module, linked to the virtual device as second variable.

The configuration of M-Bus logical structure appears from master's point of view as depicted in the lower part of the figure 18. Virtual devices "3" and "4" send two variables in their M-Bus messages: „Fabrication No." and counter status of relevant medium. Virtual device "5" sends in its M-Bus message three variables: „Fabrication No.", counter status and temperature.

General structure of M-Bus information message with readings from a virtual M-Bus device is depicted in the figure 19.

Fixed Data Header	Variable Data Blocks		
	Block 1	Block 2	Block 3
12 Byte	Fabrication No	Value Index 0	Value Index 1

Figure 19: Structure of the WM868-SJ-MS module M-Bus message

The message consists of the message header („M-Bus Header") and several variable data blocks, their number and length depend on the number and setting of variables.

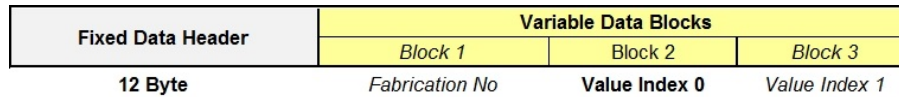The **M-Bus Header** carries identification of virtual device and other entries from the „Table of virtual M-Bus devices" (see paragraph 3.5.6). The information structure of M-Bus message header is evident from the figure 20.

Name	Description / Meaning	Length (Byte)	Example	Value
Ident. Nr.	Module M-Bus Identifier	4	55556666	66 66 55 55
Manufacturer	M-Bus Manufacturer Code	2	SFT	D4 4C
Version	Addressing Version / Generation (M-Bus standard)	1	1	01
Medium	M-Bus Medium Code	1	water	07
Access No.	Message Sequence No (+1 with each message)	1	0	00
Status	Device Error Status ("00" for non-error status)	1	"ok"	00
Signature	Encryption Type & Parameter ("00 00" for no encryption)	2	"no encryption"	00 00

Figure 20: Structure of M-Bus message header

Number of **data blocks** in the message is variable and variable could be also their length. Each message carries at least one data block with some variable (otherwise the message has no sense).

If there is a **„Fabrication"** variable value set in the record of any device from „Table of virtual M-Bus devices", the first data block of device message carries virtual meter's serial number. If „Fabrication" field is empty, appropriate data block will not be created.

Number of other data block corresponds with the number of variables („nested rows"), affiliated with the virtual device record. Each variable has its own data block in the message, its content depends on the setting of relevant „nested row" as described in the paragraph 3.5.6.

Example of variable data blocks typical structure of common water meter message with preconfigured „Fabrication" value and one variable of „water volume counter" type is depicted in figure 21.

Order	Variable (Description and Meaning)	Unit & Multiplier	Type	Data Format	Example of Coding in Data Block			
					DIF	VIF	Data	Value
1	Meter/Sensor Serial Number	Fabric. №	Instant Value	Variable	0D	78	0C 31 32 33 34 78 78 79 79 35 36 37 38	1234xxyy5678
2	Watermeter Reading Value	m³ (10⁻³)	Instant Value	32 Bit Integer	04	13	D7 00 00 00	215

Figure 21: Example of structure and content of information message data blocks

4 Operational conditions

This section of the document describes basic recommendations for transportation, storing, installation and operation of WM868-SJ-MS radio modules.

4.1 General operational risks

The WM868-SJ-MS RF-modules are electronic devices powered from an external power source that receive radio-messages with current statuses of meters/sensors through the WACO RF-network, and transmit messages to superior M-Bus control unit („Master") through the two-wire M-Bus data bus on master's request. During the operation of the modules there are following potential risks:

4.1.1 Risk of mechanical damage

The devices are covered in plastic boxes, so electronic components are not accessible for a direct mechanical damage. When installing it is necessary to ensure a sufficient space for connecting cables (including the configuration cable) and also that the cables are as short as possible (especially power and antenna cables). It is necessary to ensure the proper fastening of the module to DIN-rail with a plastic lock. In normal operation no special precautions are needed, besides avoiding of the mechanical damage from strong pressure or shocks.

Special attention is required for power, communication/signaling and antenna cables. In operation it is necessary to ensure that the cables are not stressed by mechanical tension or bending. In the case of damage of any cable isolation it is recommended to replace the cable immediately. If the module is equipped with a remote antenna on a coaxial cable, much attention should be paid for the antenna and the antenna cable as well. The minimum bending radius of the antenna cable with 6 mm diameter is 4 cm, for the antenna cable with the 2,5 mm diameter the bending radius is 2 cm. Violation of these bending parameters can lead to breach of homogeneity of the coaxial cable that could cause reducing of radio range of the device. Further it is necessary to ensure that the connected antenna cable will not stress the antenna connector of the device by tension or twist. Excessive loads can damage or destroy antenna connectors.

The module is specified for installation in normal internal premises with the temperature range of (-10 ÷ +50)°C, with humidity up to 90% without condensation. Direct installation of the equipment in outdoor areas is not possible.

4.1.2 Risk of electrical damage

Electrical installation of the module can be performed only by a person with necessary qualification in electrical engineering and at the same time trained for this device installation. The device is powered by DC power with safe voltage up to 24 V and current consumption up to 200 mA.

The power supply must meet the requirements for the safety protective transformer ČSN-EN61558-2-6. The module has an integrated protection against reversing the polarity of the supply voltage. Reversing the polarity is indicated so that after switching on the supply voltage to the module a green LED „PWR" on the front panel does not shine. Unwanted reversing the polarity of the supply voltage does not lead to damage or destruction of the device. In addition, the module is on the supply inlet equipped with a irreversible fuse (polyswitch) with the actuating current of 300 mA and over-voltage protection with 30 V switching level.

The module is not equipped by any disconnecting component – switch. It is suitable to place in installation a disconnecting component, for example a circuit breaker, which can be inserted into 24V/DC lateral of the supply or into the 230V/AC side of the supply. The primary side of the power source must be protected by automatically irreversible fuse.

4.2 The condition of modules on delivery

Modules are delivered in standard cardboard boxes. At standard term of delivery the module does not include the antenna, the power supply and cables, if required these components must be ordered separately.

4.3 Modules storage

Modules should be stored in dry rooms with a temperature range (0 ÷ 30) °C.

4.4 Safety precautions

Warning! Mechanical and electrical installation of the WM868-SJ-MS module can be provided only by a person with necessary qualification in electrical engineering.

4.5 Environmental protection and recycling

The equipment does not contain exchangeable components, which require compliance with specific rules in terms of environmental protection for their replacing, storage and disposal. Damaged, destroyed or discarded devices cannot be disposed as household waste. Equipment must be disposed of in the waste collection yards, which dispose electronic waste. Information about the nearest collection yard can be provided by the relevant local (municipal) authority.

4.6 WM868-SJ-MS module installation

The WM868-SJ-MS radio modules are enclosed in plastic casings with an IP20 degree of protection equipped by plastic locks for mounting on the DIN-rail. Casings should not be open under mounting, dismantling and normal operation.

Detailed view of the WM868-SJ-MS module from the power supply clamps side and from the rear side is shown in figure 22.
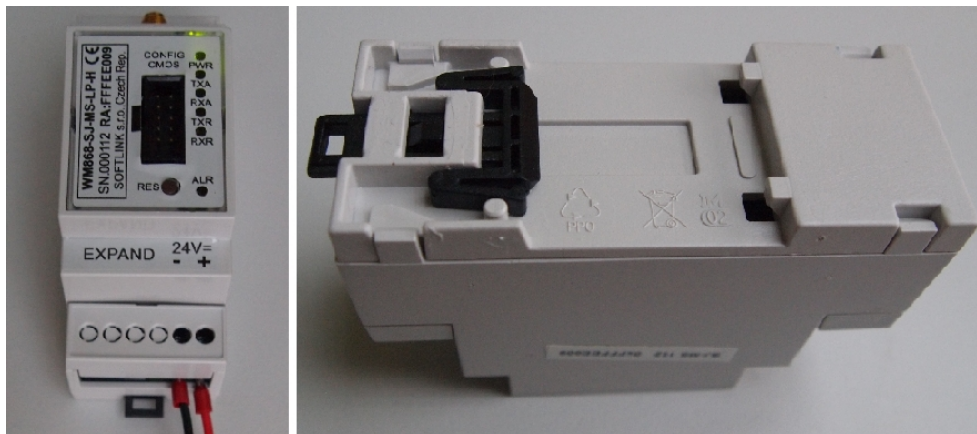

Figure 22: Detailed view of WM868-SJ-MS module

Installation of the module should be performed by the following procedure:

- installation of the module can be performed only by a person with necessary qualification in electrical engineering and at the same time trained for this device installation;
- when selecting an installation site pay attention to secure sufficient space for connection of antenna, power and signaling cables to the module (see paragraph 4.1.1 „Risk of mechanical damage"). It is necessary to keep the sufficient space for the connecting of configuration cable as well;
- when selecting a site for the module installation it is necessary to choose a place with availability of power supply. The power supply should be placed close to the module so that the feed of 24 voltage is as short as possible. Further it is necessary to consider the method of the module switching off and location of an appropriate disconnecting element (see paragraph 4.1.2 „Risk of electrical damage").
- mount the module to the selected place on the DIN-rail. Pull down black plastic lock in the bottom side of the module (outward of the module), attach the module to the DIN-rail so that the rail fits into the slot on the rear side of the module and push the black plastic lock up (inward the module);
- connect the antenna and signal cables to the module;
- make sure that the power supply is turned off and connect the power cable to the module. Verify that the polarity of power supply corresponds with the marking on the module terminals;
- check whether everything is properly connected and fasted and turn on the power supply. Green LED „Power" will shine on the module and the operation system will start up;

- perform the basic diagnostic of the module in compliance with the procedure mentioned in the paragraph 4.9 „Functional check of the module" and possibly (if the module was not pre-configured during the preparatory stage of installation) its configuration with using of the configuration cable according to the procedure described in the paragraph 3 „Configuration of the module individual parameters";
- record information about the module installation (serial number, position, picture of installation...) to the operational documentation under internal rules.

When locating installation site, selecting antenna type and antenna position it is necessary to take into account conditions for radio signal propagation in the area of installation. The conditions is possible either estimate empirically on the base of previous experience, or accomplish a measurement of the signal strength by the signal analyzer.

4.7 Module replacement

When there is necessary to replace the module due to the module failure follow this procedure:

- switch off the power supply and disconnect the power cable wires from the module;
- disconnect the signal cable and the antenna cable;
- release the module from DIN-rail by pulling down of the black plastic lock on the bottom side of the module down (outward of the module) and remove the module from the rail;
- attach the new module at the place of the original module and proceed further according to the procedure mentioned in the paragraph 4.6. Especially pay attention to the correct connection of the power cable;
- after switching power on perform the diagnostics and set-up parameters;
- label the original module as „defective" and fill in the appropriate documentation prescribed by internal rules for this case.

4.8 The module dismantling

When dismantling module turn the power supply off and disconnect the power supply cables from the module. Disconnect the signal cable and the antenna cable from the module. Release the module from DIN-rail by pulling down of the black plastic lock on the bottom side of the module (outward of the module). If there is no further use for the antenna, remove the antenna cable and the antenna. If there is no further use for the power supply, remove the power supply and the power cable. If the power supply is used for other purposes, secure power cables against short circuit (by insulation of live ends of wires or by removal of useless power branches) and connect the power supply again. After dismantling label the module properly as „dismounted" and fill in the appropriate documentation prescribed by internal rules for this case.

4.9 Functional check of the module

After putting the module into operation (or after each repair and replacing of the module) it is recommended to check module basic functionality as follows:

- check broadcasting functionality by RFAN 3.x analyzer in „Packets" or „Radar" mode (according to the analyzer documentation) with using of „test broadcasting" function described in the paragraph 3.5.7 „Setting of test broadcasting";
- check receiving of data from all WACO RF modules, whose messages the module collects and process. This check can be performed by inspection of „Table of virtual M-Bus devices, where current statuses of all variables apear at the end of each „nested row" of the table (see paragraph 3.5.6 „Setting of Table of virtual M-Bus devices"). If all variables are available and up-to date, the module receiving is apparently functional;
- when in doubt, the presence and quality of RF signal from particular module can be tested by RFAN 3.x analyzer in "Packets" or "Radar" mode (according to the analyzer documentation);
- perform overall check of transmitter and receiver functioning by testing of remote configuration via radio with using of RFAN 3.x analyzer (i.e. reading of any module's parameter by "GET" command as described in chapter 3.2 „Configuration of the module via radio");
- complex end-to-end check of the WM868-SJ-MS module functionality (including functioning of serial interface and correctness of central database) can be performed by making of trial reading of all variables and inspection of gathered data.

4.10   Operation of the WM868-SJ-MS module

The WM868-SJ-MS module performs receiving of radio messages through the WACO RF-network and communication with the M-Bus master through the M-Bus Slave wired bus fully automatically. When the RF-network is overloaded by heavy radio traffic, temporary loss of messages or short-time breakdowns of connection with some modules can occur due to signal collisions.

The greatest risks of permanent breakdown of module RF communication (or communication breakdown of local wired line) are commonly caused by human activities within the installation site. It is mainly about the following risks:

- turning off the module power (e.g. circuit breaker failure or unintentional shutdown);
- temporary or permanent shading of the antenna (e.g. due to building operations);
- mechanical damage of the module, antenna cable, antenna or M-Bus Slave signal cable by handling things at the installation site.

To eliminate these risks, it is recommended to pay close attention to selection of the installation site and choice of antenna and antenna location so that to find appropriate compromise between qualities of signal and the level of risk of mechanical damage of the module or antenna. It is necessary to carry out the installation carefully with using of high-quality cables and mounting components.

To prevent an unexpected breakdown, it is recommended to perform regular monitoring of all reading. If some of the readings are not regularly refreshed or go beyond the common steady value, it is recommended to contact the installation site caretaker and ask for the potential cause of the anomaly or perform the physical check on the installation site.

5   Troubleshooting

5.1   Possible causes of module failures

If during operation of WM868-SJ-MS module some anomaly, malfunctions or other troubles are recognized, the possible causes of the failures can be classified by following categories:

5.1.1   Power supplying failures

The module requires an external power supplying according to the specification in paragraph 2 „Technical parameters overview". Power supplying voltage is signaled by shining of green LED "PWR" on the module front panel. Malfunction or breakdown of the power supplying will cause a complete breakdown of the device. Correctness of power supplying can be checked by this procedure:

- check if there is no electricity breakdown in the building;
- check, if the power supply is "on" and properly working;
- check on the installation site whether the module is really under voltage (that means the "PWR" LED is shining);
- in case of any doubt take the measurement of the voltage.

If the reason of the failure is external power supplying system, repair the power supply or power distribution system. In case of failure of power supply, circuit breaker, surge protection (or any other protecting element) try to find out the primary cause of the failure, especially check short circuit possibility caused by penetration of humidity or water or malfunction of other device connected to the same power supply.

If the power supplying is properly working with correct voltage but the green "PWR" LED is still not shining, the module is probably out of order. Perform the replacement of the module according to the instructions in paragraph 4.7 and check functionality of the new module. If the new device works properly, label the original module as „defective" and fill in the appropriate documentation prescribed by internal rules for this case.

5.1.2   System failures

As „system failure" are considered mainly failures of module's processor, memory, internal supplying or any other failures that cause a complete breakdown of the device. If the power supplying of the module is properly working with correct voltage (green "PWR" LED is shining) but the device still does not communicate through its configuration

port and does not respond to any commands and this status will not change even after module's restart (by "RES" button on the front panel), the system failure probably occur. Perform the replacement of the module according to the instructions in paragraph 4.7 and check functionality of the new module. If the new device works properly, label the original module as „defective" and fill in the appropriate documentation prescribed by internal rules for this case.

5.1.3 Transmitter and receiver failures

Transmission and reception of RF messages is signaled by flashing of yellow "TXA" / "RXA" LEDs and red "ALR" LED on the module front panel. The "TXA" LED blinks when a radio message is transmitted, the "RXA" LED blinks when a radio-message is received. When transmitting of message is postponed by anti-collision system, the red "ALR" LED is flashing.

If the module is powered by correct voltage, the module communicates through the configuration port, responds to the configuration commands but the radio-messages from the module are still not received steadily, the possible reason of the trouble can be a failure of transmitting or receiving of radio signal. The typical indication of transmitting or receiving failures is state of „partial" functionality, that have following external signs:

- the module transfers data only from certain elements of the radio-network, data from other elements are not transferred;
- certain elements of the network do not receive data from the module;
- data from certain elements of the network are incorrect or incomplete;
- there are numerous breakdowns in the data communication (sometimes the data pass through the module, sometimes not).

All above described troubles could have on common ground, which is unreliability of radio-communication caused by one of these reasons:

- incorrect setting of transmitter parameters, mainly frequency channel, maximum number of re-translations, or transmitting power;
- permanent or occasional blocking of radio signal caused by construction works or any construction changes within the premises, or by operation around the installation site (moving of machines, cars, etc.);
- permanent, periodical or occasional interference (jamming) of radio signal from external source (another radio system in the same frequency band, or industrial disturbance).
- low level of transmitting signal caused by wrong setting or failure of transmitter;
- low level of receiving signal caused by wrong setting or failure of receiver;
- low level of transmitting and receiving signal caused by damage of antenna or antenna cable (if external antenna used).

If above described indications of unreliable radio-communication become evident, proceed with troubleshooting of the malfunctioning in following steps:

- visually check surrounding of the installation site to find out if there are any changes that can influence radio signal (e.g. new objects, things, machines...). If there are such negative circumstances, solve the trouble by reorganization of the object or by redesign of radio network;
- visually check an external antenna and antenna cable (if used), possibly replace these elements for the spare ones with proven functionality;
- check correctness of module settings, especially setting of radio parameters as described in paragraph 3.6 and perform the check of module overall functionality as described in paragraph 4.9;
- if there are breakdowns in communication with some specific element of the network, check functionality of that element according to the respective documentation;
- replace the module according to the paragraph 4.7 and perform the setting and check of overall functionality off the new module after that;
- if the module is not properly working even after its replacement for proven device and equipment, the trouble can be caused by local interference (jamming) from external source. Another possible reason could be an unsuitable setting of some configuration parameter that has not been discovered. In this case ask for your supplier, producer, or other experienced person for some form of assistance.

Appropriate level of transmitting power can be checked by comparing of its signal strength with the reference signal from another module (modules) under comparable circumstances, for example with using of signal analyzer or testing receiver placed to the suitable spot. If the signal strength is similar to the signal of reference transmitter,

then the module's transmitting power is adequate, and the reason of troubles could be in insufficient signal strength on the receiving side. Attenuation of the signal can be caused by making of some change in module installation site (e.g. turning of antenna or placing of some object nearby, installation of iron bars, rack or shelfs...) or similar changes in the installation site of receiver (GateWay). This kind of troubles can be solved by redesign of the radio network in order to secure sufficient signal reception (that means changing of antenna for better type, moving of antenna or whole device etc.).

Presence of radio-disturbance is signaled by frequent (or permanent) flashing of red "ALR" LED.

5.1.4   Data bus failures

Functioning of data bus is signalled by flashing of pair of yellow "TXR" and "RXR" LEDs, that signal transmitting of a message into the bus (flashing of "TXR" LED) and receiving of a message from the bus (flashing of "RXR" LED).

Data bus failures manifest themselves by full or partial malfunctioning of the bus communication. Module with inoperative data bus communicates through its configuration port, responds to configuration commands, but the messages from some of the connected meters (or from all of them) do not come to the radio network (or vice versa - messages from the radio network don't come to the devices on the bus.). In some cases the malfunction of the bus is partial - interruptions are either random in time or their affect is limited to only some of the connected devices (meters, sensors).

Data bus failures and breakdowns can be caused by following reasons:
- incorrect setting of data bus parameters as decribed inparagraph 3.5.5, or discrepancy between bus parameters of the module and connected device;
- mechanical damage of the bus cable;
- fault of module's link amplifier;
- worsening of the bus transmission capacity as a result of some changes or modifications of the bus (...a new device connected to bus, order alteration, wiring replacement, terminator connection/disconnection...);
- disturbance of the electrical signal within the bus by induction of the interfering signal into the bus, or troubles caused by differences of electrical potential among devices connected to the bus.

Recommendation: *Troubles with bus transmission capacity as described in the last two items generally occur especially if there is a bus with lengthy wiring and with high number of connected devices. Troubleshooting of the bus failures can be quite complicated and requires a specific knowledge and experiences. It is recommended to entrust the task to the specialist with experiences with given type of bus.*

If there is a suspicion that the operational troubles with data collection from the remote bus could be caused by failure of data bus itself, first of all check correctness of data collection system settings, especially correct identification (addressing) of individual devices within central system (master) database. If the correctness of the identification is positively checked, proceed with troubleshooting of the data bus communication malfunctioning in following steps:
- visually check whether the bus cable from the given meter/sensor is attached correctly to the module and test its functionality by ohmmeter. If the inspection of the cable shows any signs of its damage (or it is evidently inoperative), repair or replace the cable immediately;
- if the bus wiring is undamaged and messages from other devices on the same bus came to the central system correctly, check consistency of setting of bus parametres within the module configuration and within the connected meter/sensor as described in the paragraph 3.5.5 „Setting of parameters of the M-Bus Slave bus"
- if the bus is physically functional and its configuration is correct and consistent with setting of connected devices, but the communication through the bus is still non-functional, the WM868-SJ-MS module is probably defective and it is necessary to make its replacement as described in the paragraph 4.7;
- if the bus communication will not work properly even after replacement of the module, the bus is physically apparently functional, configuration of the module is correct, addressing is in harmony with setting of bus „Master", but the messages still dont pass through the bus, the bus is probably not working correctly on the data level. In this case try to make some changes in the bus setting on the „Master" side (different speed, different Inter-Byte timeout...) that is possible to make and could have some influence on the bus communication. In this case it is recommended to ask for advice/support some person with broad experiences in bus communication or module producer.

5.1.5   Troubles with data transformation

The WM868-SJ-MS module performs transformation of messages from original WACO format to M-Bus format. The main source of M-Bus data is „Table of virtual M-Bus devices", that contains records of all WACO devices

and their variables alongside with the identification of these devices and variables in M-Bus system, including complementary parameters VIF/DIF, that are necessary for coding of variables into M-Bus format.

Troubles with data transformation manifest themselves as missing or invalid readings from some virtual devices (e.g. readings are associated with incorrect device, incorrect decoded value of variable, wrong multiplier, unit, etc.).

Root cause of these troubles is always incorrect setting of „Table of virtual M-Bus devices". In case of suspicion, that the operational troubles can be linked to data transformation, check setting of parameters of the record related to the device with incorrect data in the table (see paragraph 3.5.6) and compare the settings with configuration of bus control unit („M-Bus Master") with using of relevant documentation. Both settings should be in harmony.

By inspection of the „Table of virtual M-Bus devices" can be checked, if the value of incorrectly decoded variable, that appears in the „Value" column, is correct and regularly refreshing. If the value is incorrect or not updated, check setting of the variable row in the table (correct setting of variable type from matching device/port). If the value of variable is correctly stored into the „Value" field of the table, check correctness of setting of virtual M-Bus address according to the M-Bus standard and harmony of this setting with setting of M-Bus address in M-Bus Master's database.

5.2   Troubleshooting procedure

To identify a reason of device failure or any anomaly in its operation follow this procedure:

1. No data are available from any remote RF-module. In this case it is recommended to check functionality of the module subsystems in following order:

   - check functionality of power supplying as described in the paragraph 5.1.1 „Power supplying failures"
   - check functionality of the system as described in the paragraph 5.1.2 „System failures"
   - check data bus functionality as described in the paragraph 5.1.4 „Data bus failures"
   - check transmitting and receiving functionalities as described in the paragraph 5.1.3 „Transmitter and receiver failures"

2. No data are available from only one remote RF-module. In this case it is recommended to check functionality of the module subsystems in following order:

   - check functionality of remote RF-module
   - check correctness of central application configuration related to the meter/sensor on the remote bus segment.
   - check correctness of setting of „Table of virtual M-Bus devices" as described in the paragraph 5.1.5 „Troubles with data transformation"
   - check transmitting and receiving functionalities as described in the paragraph 5.1.3 „Transmitter and receiver failures"

3. No data are available from only one virtual device (or its variable) on the remote RF-module. In this case it is recommended to check functionality of the module subsystems in following order:

   - check correctness of setting of „Table of virtual M-Bus devices" as described in the paragraph 5.1.5 „Troubles with data transformation"
   - check correctness of central application configuration related to the meter/sensor on the remote bus segment.

NOTE: The WM868-SJ-MS module is a reliable device with relatively simple and resilient construction, so that any possible failure of the device is very likely caused by external circumstances, especially installation environment, mechanical damage, excessive humidity, overvoltage of power supplying, or voltage pulses induced to the data bus. After each replacement of the module caused by its failure it is recommended to check the root cause of the failure and take necessary measures to eliminate any persisting troubles.

6 Additional information

This manual is focused on description, parameters and configuration options of radio modules WM868-SJ-MS of the WACO RF system, operating in the 868 MHz band, that are a part of the Softlink's **wacoSystem** product family. More information about all WM868 (WACO), WB169 (Wireless M-BUS), WS868 (Sigfox), or NB (NB-IoT) series of the modules can be found on the manufacturer website:

www.wacosystem.com
www.softlink.cz

If interested in any additional information related to application of radio modules of WM868, WB169, WS868 or NB series or other manufacturer's equipment for telemetry and remote reading of consumption meters, feel free to contact the manufacturer:

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